भारतीय सूचना प्रौद्योगिकीअभिकल्पना एवं विनिर्माण संस्थान कर्नूल INDIAN INSTITUTE OF INFORMATION TECHNOLOGY DESIGN AND MANUFACTURING KURNOOL

Jagannathagattu, Kurnool – 518007, Andhra Pradesh, INDIA (An Institute of National Importance under MHRD Govt. of India)



Syllabus for

B. Tech. in Mechanical Engineering *with Specialization in Design and Manufacturing* (From AY 2019-20)

DEPARTMENT OF MECHANICALENGINEERING



INDIAN INSTITUTE OF INFORMATION TECHNOLOGY DESIGN AND MANUFACTURING KURNOOL

Jagannathagattu, Kurnool-518007, Andhra Pradesh (An Institute of National Importance funded by MHRD, Govt. of India)

Institute Vision

To become a leading institute of higher learning in Information Technology enabled design & manufacturing to create technologies and technologists befitting the industries globally.

Institute Mission

To become a center of excellence pioneering in education, research & development, and leaders in design & manufacturing.

Department Vision

To build an academic and research eco system with the innovation mindset and global perspectives to cater the needs of the society in the discipline of Mechanical Engineering with prime focus in the fields of design and manufacturing.

Department Mission

To enable the graduates technically sound with the state-of- the –art curriculum and innovative teaching methods and carrying out cutting edge research in collaboration with industry and research organizations.

Scheme/Structure for B. Tech. in Mechanical Engineering *with Specialization in Design and Manufacturing*

	Semester I									
S. No.	Course Code	Course Name	Category	Ι	Р	С				
1	MAT104T	Calculus	BSC	3	0	3				
2	PHY108T	Engineering Mechanics	BSC	3	0	3				
3	INT107T	English for Communication	HMC	2	0	2				
4	COM105T	Computational Engineering	BEC	3	0	3				
5	DES101T	Concepts in Engineering Design	DES	3	0	3				
6	INT109P	Engineering Graphics	DES	1	3	3				
7	DES103T	Earth, Environment & Design	DES	2	0	P/F				
8	PHY108P	Materials & Mechanics Practice	BSC	0	3	2				
9	COM105P	Computational Engineering Practice	BEC	0	3	2				
10	INT110P	Engineering Skills Practice	BEC	0	3	2				
Total					12	23				

Semester II									
S. No.	Course Code	Course Name	Category	Ι	Р	С			
1	MAT105T	Differential Equations	BSC	3	0	3			
2	PHY107T	Engineering Electromagnetics	BSC	3	0	3			
3	MAN102T	Professional Ethics for Engineers	HMC	2	0	P/F			
4	INT108T	Science and Engineering of Materials	BEC	3	0	3			
5	ELE103T	Basic Electrical & Electronics Engineering	BEC	3	0	3			
6	DES102T	Design History	DES	2	0	2			
7	PHY107P	Engineering Electromagnetics Practice	BSC	0	3	2			
8	INT111P	Measurement & Data Analysis Practice	BSC	0	3	2			
9	DES104P	Industrial Design Sketching	BEC	0	3	2			
10	DES105P	Design Realization	DES	0	3	2			
Total					12	22			

		Semester III				
S. No.	Course Code	Course Name	Category	Ι	Р	С
1	MAT204T	Linear Algebra	BSC	3	0	3
2	ME201T	Thermal Engineering - Concepts & Applications	PEC	3	0	3
3	ME202T	Mechanics of Materials	PEC	3	0	3
4	ME203T	Basic Concepts in Manufacturing Processes	PEC	3	0	3
5	ME204T	Kinematics of Machines	PEC	3	0	3
6	ME205I	Electrical Drives	PEC	1	3	3
7	ME206P	Machine Drawing & Manufacturability Analysis	PEC	0	3	2
		Practice				
8	8 ME207P Product Realization Practice		PEC	0	3	2
Total						22

Semester IV								
S. No.	Course Code	Course Name	Category	Ι	Р	С		
1	MAT206T	Numerical Methods	BSC	3	0	3		
2	MANK201T	Engineering Economics	HMC	3	0	3		
3	ME208T	Fluid Mechanics and Hydraulic Machinery	PEC	3	0	3		
4	ME209T	Dynamics of Machines	PEC	3	0	3		
5	ME210T	Quality Inspection and Product Validation	PEC	3	0	3		
6	ME210P	Quality Inspection and Product Validation Practice	PEC	0	3	2		
7	ME211I	Sensors and Controls	PEC	1	3	3		
8	ME212P	Mechanical Design Practice	PEC	0	3	2		
Total					9	22		

		Semester V				
S. No.	Course Code	Course Name	Category	Ι	Р	С
1	MANK301T	Entrepreneurship and Management Functions	HMC	3	0	3
2	ME301T	Heat Transfer	PEC	3	0	3
3	ME302T	Automation in Manufacturing	PEC	3	0	3
4	ME302P	Manufacturing Automation Practice	PEC	0	3	2
5	ME303T	Machine Tool Technology	PEC	3	0	3
6	ME304T	Design of Machine elements	PEC	3	0	3
7	ME305I	Microprocessors and Controllers	PEC	1	3	3
8	ME306P	Fluid Mechanics and Heat Transfer Practice	PEC	0	3	2
Total					9	22

		Semester VI				
S. No.	Course Code	Course Name	Category	Ι	Р	C
1	DES302T	Design for Quality and reliability	DES	3	0	3
2	ME307T	Computational Methods in Engineering	PEC	3	0	3
3	ME307P	Mechanical Design Simulation Practice	PEC	0	3	2
4	ME308T	Thermal Energy Systems	PEC	3	0	3
5	ME308P	Thermal Engineering Practice	PEC	0	3	2
6	MExxxT	Elective – I	PEC	3	0	3
7	MExxxT	Elective – II	PEC	3	0	3
8	INT303	Product Design Practice	PCD	0	3	2
Total 15						21

	Semester VII									
S. No.	Course Code	Course Name	Category	Ι	Р	С				
1	INT404	Internship	PCD	-	-	5				
2	XXxxxT	Free Elective – I	PEC	3	0	3				
3	DES401K	Design Project	DES	-	-	5				
Total					6	13				

		Semester VIII				
S. No.	Course Code	Course Name	Category	Ι	Р	С
1	MExxxT	Elective – III	PEC	3	0	3
2	XXxxxT	Free Elective – II	PEC	3	0	3
3	XXxxxT	Design Elective	DES	3	0	3
4	INT405	Project	PCD	-	-	10
Total				9	0	19

List of Electives

S. No.	Course Code	Course Name	Category	Ι	Р	С
		Department Electives				
1	ME501T	Mechanical Vibrations	PEC	3	0	3
2	ME502T	Advanced Solid Mechanics	PEC	3	0	3
3	ME503T	Computer Aided Design and Manufacturing	PEC	3	0	3
4	ME504T	Modern Manufacturing Technology	PEC	3	0	3
5	ME505T	Operation Research	PEC	3	0	3
6	ME506T	Computational Fluid Dynamics	PEC	3	0	3
7	ME507T	Optimization techniques for Mechanical Engineers	PEC	3	0	3
		Free Electives				
1	ME508T	Automobile Engineering Systems	PEC	3	0	3
2	ME509T	Non-linear Dynamics	PEC	3	0	3
3	ME510T	Operations and Supply Chain Management	PEC	3	0	3
		Design Electives				
1	ME512T	Design Intelligent Systems	PEC	3	0	3
2	DS402	Sustainable Design	DES	3	0	3

*In addition to the above prescribed electives, the student can enrol for the courses offered as part of M.Tech in Smart Manufacturing with the consent of the Faculty and prior approval of HoD.

Distribution of the courses:

S. No.	Course category	Credit distribution	Credit distribution in %
1	Basic Science Course (BSC)	24	14.6%
2	Basic Engineering Course (BEC)	15	9.1%
3	Design Course (DES)	21	12.9%
4	Humanities and Management Course (HMC)	08	4.9%
5	Professional Engineering Course (PEC)	79	48.1%
6	Professional Career Development (PCD)	17	10.4%
	Total	164	100%



SYLLABUS

Course Title	Thermal Engineering – Concepts & Applications	Course No	ME201T
Course category	PEC	Structure (IPC)	3-0-3
Offered for	B.Tech, MDM	Status (Core/Elective)	Core
Prerequisite	Nil	Effective from	July 2019
Course Objective	The objective of this course is to thermodynamics. Also, develop th basic thermodynamic cycles.	provide insights on basic particular provide insights on basic particular provide in a provide the providet the provide the provide the providet the p	principles and concepts of systematic way to analyze
Course Outcomes	At the end of the course, the studer 1. Identify different forms of energ 2. Describe the laws of thermodyna 3. Apply the laws of thermodynan systems. 4. Estimate the properties of ideal g 5. Analyze the thermodynamic cyc	nt will be able to: gy. amic principles related to var nics to estimate the performa gases and pure substances. eles of various thermal system	ious thermal systems. nce parameters of thermal
	Fundamentals: System, Control v Zeroth law, Principles of Thermor forms of work.(9) First law: First law Analysis of Cl energy, Enthalpy, Free expansion SFEE, Examples of steady flow Throttling Valve and Heat Exchange	losed System for Cyclic & n a process, Application of Fin w devices: Nozzle, Diffuse gers, PMM-I, Limitations of	cess, Cycle, Equilibrium, rgy, Heat, Work, Different on-cyclic process, Internal rst law to flow processes, er, Turbine, Compressor, first law.(11)
Contents of the course (With approximate break up of hours)	Second law: Qualitative differed Refrigerators, Heat Pumps, Kelv Cycle, Reversible &Irreversible Entropy, Demonstration that entro Available and unavailable energe equations. (11) Pure Substances and Gases: Proper temperature and constant pressu Superheated tables, Mollier chart, 1	ence between the heat ar vin-Planck & Clausius Stat cycles. Entropy: Clausius opy is a property, T-s diagr gy, Concept of irreversibil erties of pure substances, W re heating, Use of steam Ideal gas and their mixtures,	nd work, Heat Engines, mements, PMM-II, Carnot inequality, Definition of ram, Isentropic efficiency, ity and lost work, T-ds ater and steam - Constant tables: Saturation tables, Real gases. (6)
	Thermodynamic Cycles: Analysis – Comparison with Carnot cycle. (of Otto cycle, Diesel cycle, 5)	Dual cycle, Brayton cycle
Textbooks and References	 P. K. Nag, "Engineering Therr. Y. A. Cengel, and M. A. Be McGraw-Hill, 8thEdition, 201 C. Borgnakke and R. E. Sonn Wiley, 2009. Moran, Shapiro, Boettner and 8th Edition Wiley 2015 	nodynamics," McGraw-Hill, oles, "Thermodynamics: Ar 11. tag, "Fundamentals of Therr Bailey, "Principles of Engir	6th Edition, 2013. Engineering Approach", nodynamics," 7th Edition, teering Thermodynamics",

Course Title	Mechanics of Materials	Course No	ME202T	
Course category	PEC	Structure (IPC)	3-0-3	
Offered for	B.Tech, MDM	Status (Core/Elective)	Core	
Prerequisite	Engineering Mechanics	Effective from	July 2019	
Course Objective	The objective of this course is to intro the simplified case of elastic solids.	duce the principles of c	continuum mechanics as applied to	
Course Outcomes	 At the end of the course, a student will be able to: Describe the material behavior under different kind of static loading conditions Analyze the problems related to deformation of elastic bodies Design simple structures under static loadings, i.e. beams, shafts, columns, etc. Design the structures under combined loads Apply the different failure theories based on the application 			
Contents of the course (With approximate break up of hours)	Review of equilibrium, compatibility, Pure bending of beams – shear force cross- sections; Deflection of beams.	stress and strain at a po e and bending moment (11)	oint and Mohr's circle. (4) diagrams; beams with composite	
	Torsion of circular cross sections – application to pressure vessels and spr Theory of failures for ductile and britt	pplication and transmis ings.(10) le materials. (6)	sion of torque; Combined loads –	
	Buckling of columns – eccentric loadi Virtual work – Energy methods – prin	ng; various end constra	ints. (6) (5)	
Textbooks and References	 F. P. Beer, E. R. Johnston, J. T. McGraw Hill, 7th Edition, 2014. R. C. Hibbeler, "Mechanics of M A. C. Ugural, "Mechanics of Ma J. M. Gere and S. Timoshenko, " Edition, 1997. W. Nashand, N. Malik, "Streng 	Γ. Dewolf, and D. Ma laterials," Prentice Hall terials," Wiely, 1st Edir Mechanics of Material th of Materials", McC	zurek, "Mechanics of Materials," , 8th Edition, 2010. tion,2007. s", PWS Publishing Company, 4th draw Hill Education Pvt. Ltd, 4th	

Course Title	Basic Concepts in Manufacturing Processes	Course No	ME203T	
Course category	PEC	Structure (IPC)	3-0-3	
Offered for	B.Tech, MDM	Status (Core/Elective)	Core	
Prerequisite	Science and Engineering of Materials	Effective from	July 2019	
Course Objectives	Students will learn the fundament processes and interpret the produ- manufacturing processes.	als of conventional and uct requirements to sel	non-traditional manufacturing ect and/or synthesize suitable	
Course Outcomes	At the end of the course, a student 1. Determine the appropriate manu 2. Analyze the suitability of a m designed specifications 3. Perform cost analysis for vari processing the material.	will be able to: ifacturing process(es) for nanufacturing process to ious manufacturing pro	t the product to be made. to convert the raw material to cess to minimize the cost of	
Contents of the course	Introduction of manufacturing	processes, manufactur	ing process categories and	
(With approximate	classification, Basic concepts an	nd applications of cast	ing, Glass working, shaping	
break up of hours)	processes for plastics, processing polymer matrix composites and rubber, powder metallurgy. (7)Metal forming; bulk deformation processes and sheet metal working, Theory of metal machining, machining operations and machine tools, cutting tool technology. (12)			
	Fundamental of welding process, brazing, soldering and adhesive bonding. (5)			
	Additive manufacturing processes, semi-conductor fabrication, micro and nano fabrication and advanced manufacturing processes. (12)			
	Manufacturing Engineering, Econ (6)	nomic modelling and co	ost analysis, Process selection.	
Textbooks and References	 S. Kalpakjain, and S.R. Schmi Edition, Pearson India,2009. M. P. Groover, "Principles of 	idt, "Manufacturing Eng f Modern Manufacturin	ineering and Technology," 7th	
	2014.		g, 5th Eutlon, whey, mera,	
	3. E. P. DeGarmo, J. T. Black, a in manufacturing." John Wiley	nd R. A. Kohser, "DeG / & Sons.2011	armo's materials and processes	
	 4. Gibson, D. W. Rosen, and B. Stucker, "Additive manufacturing technologies," Springer 2010 			
	 Stephenson, David A., and John S. Agapiou, "Metal cutting theory and practice," Vol. 68, CRC press,2005. 			
	6. S. Kalpakjain, and S. R. S. materials," 5th Edition. Pearso	Schmid, "Manufacturin n Education, India.2010	g processes for engineering	

Course Title	Kinematics of Machines	Course No	ME204T	
Course category	PEC	Structure (IPC)	3-0-3	
Offered for	B.Tech, MDM	Status (Core/Elective)	Core	
Pre-requisite	Engineering Mechanics	Effective from	July 2019	
Course Objective	The objective of this course is to provi	le the fundamentals to und	erstand the kinematics of	
	various mechanisms and machineries.			
Course Outcomes	At the end of the course, a student will b	e able to:		
	1. Demonstrate a good understanding of	the principles of rigid body	motion	
	2. Predict the degrees of freedom, velo	city and acceleration of dif	fferent mechanisms using	
	graphical or analytical methods.			
	3. Synthesize the four bar and slider	crank mechanism using	path synthesis, function	
	generation and point synthesis.			
	4. Analyze the problems related to cam and follower motions.			
	5. Illustrate different types of gears, gear trains and analyze the speed of gear train.			
Contents of the cours	eIntroduction to mechanisms-rigid body	motion-joints, pairs and	d couplings; Constraints,	
(With approximate	mobility and degree of freedom, Kutzba	ch and Grubler criterion, Gr	ashof's law, Inversions of	
break up of hours) different mechanisms (10)				
	Kinematics (Desition Valuatity and Acc	alamation) of mixed hadiag	analytical and anophical	
	methods (12)	eleration) of rigid bodies -	- anarytical and graphical	
	inethous. (12)			
	Kinematic synthesis of mechanisms, Point synthesis, path synthesis and function generation			
	(10)		C C	
	Gears, Gear trains and cams (10)		~ ~	
Textbooks and	1. S. S. Rattan, "Theory of Machine	s," Tata McGraw-Hill, 20	05.	
References	2. J. S. Rao, and R. V. Dukkipati,	"Mechanism and Mach	ine Theory," New Age	
	International, 2006.			
	3. A. Ghosh and A. K. Mallik, "T	heory of Mechanism and	d Machines," Affiliated	
	East –West Press Private Ltd., 20	09.		
	4. T. Bevan, "Theory of Machines,"	Pearson Education, 3rd Ed	dition, 2009.	

Course Title	Electrical Drives	Course Number	ME205I
Course category	PEC	Structure (IPC)	1-3-3
Offered to	B.Tech, MDM	Status (Core/ Elective)	Core
Prerequisite	Basic Electrical & Electronics Engineering	Effective from	July 2019
Course Objective	In this course, the fundamental applica systems will be studied as applied to me	tions of electro-mechanical a	and power electronic
Course Outcomes	 At the end of the course, a student will be able to: 1. Understand the working principles of power electronic rectifiers, converters and inverters operate. 2. Understand the control mechanism of electrical drives. 3. Analyze the performance of DC and AC machines. 4. Design the control algorithms for electric drives to achieve the regulation of torque, speed, or position in the above machines. 5. Develop Simulink® models which dynamically simulate electric machine, drive systems and their controllers. 		
Contents of the course (With approximate break up of hours)	Systems and their controllers. <u>Theory:</u> The working principle of various power electronic converters (4) Basic concepts of different types of electrical machines and their performance and Speed-Torque characteristics of various types of load and drive motors (4) Basic concepts of special machines such as Stepper motor, Permanent magnet brushless motors, Servo motor. (4)		
	Practice:The following experiments will be cond1. Explanations of basic electrical massimultingSIMULINK2. Speed control of DC Shunt Motor3. Study of Fully Controlled and Semi C4. Study of Half Bridge and Full Bridge5. Study of Single-phase Sine PWM Inv6. Study of 3 phase Square & Sine PWM7. Study of DC to DC Buck Converter at8. Speed Control of BLDC Motor9. Study of Four Quadrant Operation of10. Speed control of 3-Phase Induction11. Study of Stepper Motor Control12. Load Test on Three Phase Squirrel C13. FPGA based Motor Controller14. Project presentation (any related pointInductor coil designing	lucted: achine terms and Introduction Controlled Rectifier Inverter Verter M Inverter and Boost Converter DC Drive Motor using V/F Control Cage Induction Motor	on about MATLAB, d Different ranges of
Textbooks and References	 R. Krishnan, "Electric Motor Drive Hall, 2001. N. Mohan, "Electric Drives: An Integ M. Rashid, "Power Electronics: C Prentice Hall, 2003. J. P. Agrawal, "Power Electronic Sys 	es: Modelling, Analysis, an grative Approach", MNPERE Circuits, Devices & Applica tems: Theory and Design," P	d Control," Prentice E, 2001 ations", 3rd Edition, Pearson, 2013.

Course Title	Machine Drawing and Manufacturability Analysis Practice	Course No	ME206P
Course category	PEC	Structure (IPC)	0-3-2
Offered for	B.Tech, MDM	Status (Core/Elective)	Core
Prerequisite	Engineering Graphics	Effective from	July 2019
Course Objective	The objective of this course is to familiarize the students on basics of technical drawing such as part and assembly drawing of different machine elements using drawing instruments. Also, provide the knowledge in 3D modeling and industrial drafting using commercially available software.		
Course Outcomes	At the end of the course, a student will be a 1. Develop 3D models of machine compon 2. Digitize existing products using reverse 3. Create assembled and exploded views of 4. Analyze the machine component design ease of assembly using 3D models	able to: ents and generate 2D draven engineering f machine components for its manufacturability.	wing from 3D models , environmental impact and
Contents of the course	Machine drawing:		
	 Introduction to Machine drawing and Conventional representation of different materials and threaded joints Orthographic projections of different part drawings. Generating 2D drawings from 3D models and create production drawings using standard notations. Assembly drawing of simple machine components like cotter and sleeve joint. Assembly drawing of knuckle joint. 		
	Modelling using CATIA:		
	 Drafting: Development of part dra orthographic and isometric. Modeling machine components in 3 concepts. Modeling machine components in 3I design concepts 	wings for various com D modeling software u D modeling CATIA softv	ponents in the form of using feature-based design ware using Boolean based
	 Assembly Modelling of cotter and slubased design concepts. Assembly Modelling of knuckle joint i 	eeve joint in 3D modelinn 3D modeling software	ng software using feature-
	 Term project on assembly modeling block, footstep bearing, connecting rod 	of different components l, clutch, Oldham couplin	like screw jack, plumber g, etc.
Textbooks and References	 N.D Bhatt, "Engineering Drawing", Cl K.L. Narayana, P. Kannaiah, K.Venka 2015. 	narotar Publishing house, ta Reddy, "Machine Dra	2017. wing", New age company,
	 S. Bogolyubov. A. Voinov., "Enginee 2001. D. E. Hewitt., "Engineering Drawing a Press Ltd,2006. Boothroyd G., Dewhurst P., and Kni 	ering Drawing", Van Nor and Design for Mechanica ght W. A., "Product De	strand Reinhold Company, al Technicians", Macmillan esign for Manufacture and
	Assembly", 3rd Edition, CRC Press,20	10.	-

Course Title	Product Realization Practice	Course No	MEC207P
Course category	PEC	Structure (IPC)	0-3-2
Offered for	B.Tech, MDM	Status (Core/Elective)	Core
Prerequisite	Design Realization	Effective from	July 2019
Course Objective	Students will gain a practical know	wledge of various man	nufacturing processes in a hands-on
	environment through experiments a	and simulations.	
Course Outcomes	At the end of the course, a student	will be able to:	
	1. Understand the basic manufacture	ring processes.	
	2. Accustom to the handling of Ma	chine tools.	
	3. Realize the products using prima	ary manufacturing proc	esses
	4. Understand the 3D printer basics	5.	
Contents of the course	The following experiments will be	conducted:	
	1. Realization of Cylindrical Part	s using Traditional Lat	he (Turning operation)
	2. Realization of Cylindrical Part	s using Traditional Lat	he (Step Turning operation)
	3. Realization of Cylindrical Part	s using Traditional Lat	he (Threading operation)
	4. Realization of Cylindrical Part	s using Traditional Lat	he (Taper Turning operation)
	5. Making of Square box with GI	sheet by using Sheet N	Aetal Bending Practice
	 Making of Rectangular box w Bending Practice 	ith required dimension	as of GI sheet by using Sheet Metal
	7. Practice on Universal Milling I	Machine (Facing opera	tion)
	8. Gear Cutting by using indexing	g on Universal Milling	Machine
	9. Machining on CNC Router cur	n Milling machine	
	10. Developing a physical model b	y using Fusion Deposi	tion Modelling (3D Printer)
Textbooks and	1. E. P. DeGarmo, J. T. Black, a	and R. A. Kohser, "De	Garmo's materials and processes in
References	manufacturing", John Wiley &	Sons,2011.	_
	2. M. P. Groover, "Principles of I	Modern Manufacturing	", 5th Edition, Wiley, 2014
	3. S. Kalpakjain, and S. R. Schn 5th Edition, Pearson Education	nid, "Manufacturing pr	rocesses for engineering materials",
1			

Course Title	Engineering Economics	Course No		
Course category	HMC	Structure (IPC)	3-0-3	
Offered to	B.Tech All branches	Status (Core/Elective)	Core	
Prerequisite	Nil	Effective from	July 2019	
Course	To develop the basic understa	To develop the basic understanding of various concepts of economics to apply them to		
Objective	engineering thought and compre-	ehend decision making.		
Course Outcomes	 After completing the course, a s 1. Understand and coordinate 2. Take decisions independent 3. Appraise economic influence 4. Use accounting information 5. Apply futuristic economic v 	ompleting the course, a student is empowered to: derstand and coordinate his engineering acumen with economic aspects. ce decisions independently on various aspects of an enterprise functioning praise economic influences on decision making e accounting information for in the process of decision making ply futuristic economic value in the decision making		
Contents of the course (With approximate	Economics for Engineering: economics Micro, macro, dem national income, per capita inco banking: types of banks, signific	s for Engineering: Understanding concepts with reference to engineering: s Micro, macro, demand and supply, relationship with price, market structures, ncome, per capita income, GDP, NDP, BOP, Fiscal (taxes) and monetary policies, types of banks, significance of stages of business cycle to engineering. (4)		
break up of hours)	 Engineering Economic Decisions: Concepts and types of trade, business and industry - of organization of business – Economic decision-making process – Strategic eco decisions (case study) – Principles of economic decisions – Factors influencing dec Economic and non-economic. (4) Accounting for Engineers: Financial goals of business – Cash flows: inflow & out Recurring & non-recurring – Revenues & Expenses – The income statement – Classif of assets & liabilities – Types of shares - The Balance sheet. (6) Understanding Financial Statements: Significance of Understanding financial state from Engineering perspective - Ratios of Profitability, solvency, liquidity and maximization, leverage and turnover. Earnings available to equity shares – Decision r based on understanding of financial statements. (6) Depreciation: Meaning – Reasons - Types – depreciation as non-cash expense – Depre as fund for investment - Methods: Straight line, diminishing balances and sinking Decision making on the choice of methods. (4) 			
Cost concepts and Behavior: Meaning of cost – Cost classification: Fun statement – Decision making using cost statement – Tenders - Fixed and other classifications – Decision making using cost behavior: Marginal cost si graphical representation, MS, Profit statement, Sales for Desired profit – F uses – Decision making using BEP. (6)			ssification: Functional – Cost rs - Fixed and variable costs – Marginal cost statement - BEP, sired profit – P/E ratio and its	
	Capital Budgeting: Significance of financial goals for engineers – concept of Budgeting – Meaning and significance of Capital budgeting decisions – Principles of investing - Traditional methods: payback period and Accounting Rate of Return – Rate of return analysis – Decision making using payback and ARR.(6)			
	Present Worth Analysis: Methods of financing – concept of cost of capital – Overall cost of capital rate as discounting rate - Time value of money – Present worth analysis – Annual Equivalent Analysis - Decision making based on NPV and IRR. Evaluation of Social benefit and social cost projects –B-C Ratio. (6)			
Textbooks and References	 Samuelson P A, Nordhans W Chan S Park, "Contemporary John A. White, Kellie S. Gr "Fundamentals of Engineering Blank Tarquin, "Engineering 	D, "Economics", McGraw Hill Engineering Economics", Pren rasman, Kenneth E. Case, Kim g Economic Analysis", First Ec Economy", 6th Edition. McGra	, 1995. tice Hall, 2011. LaScola Needy, DavidB. Pratt, lition, Wiley, 2014. w-Hill, 2005.	

Course Title	Fluid Mechanics and Hydraulic Machinery	Course No	ME208T	
Course category	PEC	Structure (IPC)	3-0-3	
Offered for	B.Tech, MDM	Status (Core/Elective)	Core	
Pre-requisite	Engineering Mechanics	Effective from	July 2019	
Course Objectives	In this course, the students will learn the dynamics and apply the concepts to fl machinery such as Turbines and Pumps.	e principles and concep ow measuring devices	pts of fluid statics and , pipes, and hydraulic	
Course Outcomes	 After completion of the course, the student will be able to: Understand the concepts of fluid statics and dynamics. Apply the concepts of fluid statics and dynamics to various engineering applications and low measuring devices. Understand the concepts of laminar & turbulent flows and boundary layer formation. Understand the working principles of hydraulic devices such as Turbines and Pumps. Analyze the performance parameters of hydraulic devices. 			
Contents of the course (With approximate break up of hours)	Fluid Statics: Physical properties of fluids Vapour Pressure and their influence on fl pressure measurement, Analysis of submerg	- Specific Gravity, Viso luid motion, Basic equa ged surfaces – Buoyancy	cosity, Surface Tension, ations of hydrostatics – y and stability. (10)	
	Fluid Kinematics and Dynamics: Classification of Flows, Stream function, potential, Conservation of mass, momentum and energy, Application of Be Equation and Momentum equations, Measurement of flow: Venturi-meter, Orific and Pitot Tube (10)			
Flow through Pipes and the Concept of Boundary layer: Reyr pipes, Pipe connections, Total Energy Line, Hydraulic Grad Laminar & Turbulent Boundary Layer, Boundary Layer separation. (8)			s Experiment, Losses in Line, Water hammer, kness, Boundary layer	
	Hydraulic Turbines: Impact of jets, Classification of Turbines, Pelton Wheel, Francis Turbine, Kaplan Turbine, Velocity diagrams, Governing of Turbines, Unit and Specific Quantities, Geometric Similarity, Cavitation, Performance characteristic curves. (9)			
	Hydraulic Pumps: Classification of rec principles, Velocity triangles, Losses and Parallel, Performance characteristic curves,	ciprocating and centrif Efficiencies, Specific S NPSH, Cavitation. (5)	fugal pumps, working peed, Pumps in Series,	
Textbooks and References	 S K Som, Gautam Biswas and S Cha Fluid Machines", McGraw Hill, 3rd ed Robert W. Fox, Philip Journal Pritchard Mechanics", 8th Edition, Wiley India P Merle C Potter, David C Wiggert and Cengage Learning India; 4th edition, 20 Streeter V.L., Benjamin Wylie, Bedfor Edition, 2017. P. N. Modi and S. M. Seth, "Hydrau 	Akraborty, "Introduction ition, 2011. d and Alan T. McDonald vt. Ltd.,2013. l Bassem H Ramadan, 2012. d K.W., "Fluid Mechanic alics & Fluid Mechanic	to Fluid Mechanics & l, "Introduction to Fluid "Mechanics of Fluids", ics", McGraw Hill, 9th s Including Hydraulics	

Course Title	Dynamics of Machines	Course No	ME209T		
Course category	PEC	Structure (IPC)	3-0-3		
Offered for	B.Tech, MDM	Status (Core/Elective)	Core		
Prerequisite	Engineering Mechanics, Kinematics of Machines	Effective from	July 2019		
Course Objective	The objective of this course is to le analysis of mechanism and analyze dy clutches, brakes and governors and als	earn the fundamentals of machinery su o basics of vibration theory of the second secon	of static and dynamic force ch as gyroscopes, flywheels, ory.		
Course Outcomes	 At the end of the course, the student w 1. Analyse the forces in different mech 2. Apply the analytical and graphical engines. 3. Design different machinery such flywheels. 4. Understand the concepts of vibratio Dynamics of rigid body in plane at analysis of slider crank mechanism. (4) 	e course, the student will be able to: orces in different mechanisms. alytical and graphical methods for balancing of rotating and reciprocating erent machinery such as gyroscopes, clutches, brakes, governors and <u>ne concepts of vibration.</u> igid body in plane and planar mechanisms – static and dynamic force or crank mechanism. (4)			
Contents of the Course (With approximate break up of hours)	Gyroscopes, effect of precession motion on the stability of moving vehicles such as motor car, motor cycle, aero-planes and ships. (7) Turning moment diagram and flywheel analysis. (4)				
	Clutches-single plate, multi-plate and centrifugal clutch, Simple block brakes, Band brake, internal expanding brake, braking of vehicle. Dynamometers – absorption and transmission types. (7)				
	Governors-spring loaded and gravity-controlled governors. (5) Review of vibrations; free vibrations and harmonically excited vibration of single degree of				
	freedom system; Vibration isolation. (8)				
Textbooks and References	 S. S. Rattan, "Theory of Machines J. S. Rao, and R. V. Dukkipa International, 2006. A. Ghosh and A. K. Mallik, "The West Press Private Ltd., 2009. T. Bevan, "Theory of Machines," 1 S. S. Rao, "Mechanical, Vibratic 	," Tata McGraw-Hill, 20 ti, "Mechanism and M cory of Mechanism and Pearson Education, 3rd E ons" 6th edition Pearso	05. fachine Theory," New Age Machines," Affiliated East – Edition, 2009. n Education 2017		

Course Title	Quality Inspection and Product Validation	Course No	ME210T
Course category	PEC	Structure (IPC)	3-0-3
Offered for	B.Tech, MDM	Status (Core/Elective)	Core
Pre-requisite	Nil	Effective from	July 2019
Course Objective	To impart knowledge on inspection, measurement, products	quality control, validation	and certification of
Course Outcomes	 At the end of the course, a student will be able to: Understand various metrology principles and techniques Acquire the knowledge to select suitable techniques and equipment to inspect and to ensure product quality Acquaintance with various quality control methodologies, standards and certifications. Understand the Inspection and Validation practices adopted in various industries through Case studies 		
Contents of the course (With approximate break up of hours)	Basic concepts: Measurement and inspection; Ro Length standards; Gauges and comparators; L tolerances. (10) Measurement Practices: Optical metrology and la straightness and form errors; Surface finish m Metrology; Nano-measurements. (10) Statistical Methodologies: Graphical methods, S Analysis of variance, Sampling and acceptance. (8) Standards and Certifications: BIS, ISO, SAE, ASM	ble of metrology in quality inear and angular measu easurements; CMM; Visio tatistical control charts, Ro) 1E, ASTM, IEEE. (6)	assurance; Errors; rements; Fits and rement of flatness, on applications in egression analysis,
Textbooks and References	 Case studies: Inspection and Validation practices a T. G. Beckwith, R. D. Marangoni, and J. 6thEdition, Pearson Higher Education, 2007. R. K. Jain, "Engineering Metrology", Khanna J D. J. Whitehouse, "Hand book of surface Press,2010. G. T. Smith, "Industrial Metrology", Springer, A.M. Badadhe, "Metrology and Quality Control", Kha 	H. Lienhard, "Mechanica Publishers, 20thEdition,201 e and nanometrology", 2 2002. ol", Technical Publications, unna Publishers, 8thEdition,	. (0) al Measurements", 4. and Edition, CRC 2006. 2008.

Course Title	Quality Inspection and Product Validation Practice	Course No	ME210P
Course category	PEC	Structure (IPC)	0-3-2
Offered for	B.Tech, MDM	Status (Core/Elective)	Core
Pre-requisite	Nil	Effective from	July 2019
Course Objective	Students will learn to Calibrate and understand the sources of various measurement errors and familiarize with the use of metrological equipment.		
Course Outcomes	 At the end of the course, a student will be able to: 1. Identify the suitable metrology instruments, gauges, and tools 2. Calibrate and understand the sources of various measurement errors 3. Apply various statistical control charts in process control. 		
Contents of the course	 The following experiments will be performed in this F Error mapping of measuring Instruments and aluminum rod using Vernier height gauge and Dia Calibration of Inside micrometer and Digital mic of Specimen (Washer) Measuring and Comparing the Depth & Thicknes Measuring and comparing the internal dimensitive Telescopic gauge Comparing Flatness measurement using Spirit Specimen Temperature Measurement during the machining Measuring the Angles of the specimen by using B Calibration of dial gauge & bore gauge and measure Measurement of roundness and cylindricity of the 	Practice session: I measurement of Line al Vernier crometer by measuring I s of Gear tooth with The ions of specimens (Gea level and Sine bar find operation using Infrared evel Protractor urement of internal dimen- e specimen.	ear dimensions of nternal dimensions oretical Values ar block, Pipe) by ding angles of the gun nsions and bores.
Textbooks and References	 T. G. Beckwith, R. D. Marangoni, and J. H 6thEdition, Pearson Higher Education. R. K. Jain, "Engineering Metrology", Khanna Pul 3. R. C. Gupta, "Statistical Quality Control", Khann 	. Lienhard, "Mechanica olishers, 20thReprint,201 a Publishers, 8 th Edition,2	al Measurements", 4. 2008.

Course categoryPECStructure (IPC)1-3-3Offered forB.Tech, MDMStatus (Core/Elective)CorePrerequisiteNilEffective fromJuly 2019Course ObjectiveThe objective of this course is to ensure that the students will be able to identify the suitable sensor for a particular measurement and identify the associated
Offered forB.Tech, MDMStatus (Core/Elective)CorePrerequisiteNilEffective fromJuly 2019Course ObjectiveThe objective of this course is to ensure that the students will be able to identify the suitable sensor for a particular measurement and identify the associated
PrerequisiteNilEffective fromJuly 2019Course ObjectiveThe objective of this course is to ensure that the students will be able to identify the suitable sensor for a particular measurement and identify the associated
Course Objective The objective of this course is to ensure that the students will be able to identify the suitable sensor for a particular measurement and identify the associated
suitable sensor for a particular measurement and identify the associated
survoire sensor for a particular measurement and identify the associated
instrumentation devices and controllers. In addition, provides knowledge to work in
LabVIEW and to make automated measurement. It also introduces DAQ based
measurement in the instrumentation and different control scheme used in the
mechanical engineering.
Course Outcomes At the end of the course, the student will be able to:
1. Select a suitable sensor for a particular instrumentation task
2. Design signal conditioning circuit and calibrate the sensor
3. Design, analyze and implement virtual instrumentation.
4. Construct an automated measurement setup
5. Choose the right actualing system for a various applications.
course and transducers and transducers classifications
(With approximate
(with approximate break up of hours) Sensors and Transducers: Flow temperature force pressure and torque sensors
Current torque and speed measurements using digital measurement techniques
Ontical sensors Lasers photo-detectors and ontical fibre as sensors
Optical sensors-Lasers photo-detectors and optical note as sensors
Calibration methods various errors of instrumentation error analysis error plots and
application of linearization principles data loggers and actuators
Virtual instrumentation, integration of filters and signal conditioners and dat
acquisition.
Sensor based Control: Types of controllers, electrical, pneumatic and hydraulic prim-
movers and associated control hardware, closed loop control of microcomputer-based
drives. Relay control systems and PLC systems and programming, control including
sequence control. Sensor based control of various actuators, mechatronic devices and
autonomous mobile robots.
Textbooks and 1. Thomas G Beckwith, Roy D Marangoni, John H. Lienhard V., "Mechanica
References Measurements", Pearson Prentice Hall, 2009.
2. Doebelin, "Measurement systems: Applications and Design", 5th Edition, McGrav
Hill, 2004.
3. Ian R. Sinclair, "Sensors and Transducers", Elsevier, 2001, ISBN: 978-0-7506
4932-2. 4 Jan S. Wilson "Senson Technology Hendhools" Norman 2004 ISDN
4. Jon S. Wilson, Sensor Technology Handbook, Newnes, 2004, ISBN
5 Bijov K Ghosh T I Tarn Ning Xi "Control in Robotics and Automation: Sensor
Based", 1st Edition, Academic press.

Course Title	Me	chanical Design Practice	Course No	ME212P	
Course category	PE	С	Structure (IPC)	0-3-2	
Offered for	В.7	Tech, MDM	Status (Core/Elective)	Core	
Pre-requisite	Nil		Effective from	July 2019	
Course Objective	Stu	dents will gain practical knowledg	ge on the strength of m	naterials under different loadings,	
	and	l the kinematics and kinetics of vari	ous mechanisms and m	achineries.	
Course Outcomes	At	the end of the course, a student will	be able to:		
	1.	Understand the behavior of materi	als under different kind	s of loading conditions.	
	2.	Apply the principles of balancing of	of masses to various lin	ks, mechanisms and engines.	
	3.	Analyze the principles of cam & for	ollower motion and gyr	oscopic effect.	
	4.	Evaluate the moment of inertial of	rod, and frequency of s	Single degree of freedom system.	
Contents of the	The	e following experiments will be con	iducted to:		
Course	1	Estimate the Applied torque of give	en motorized Gyroscor		
	$\frac{1}{2}$	Study the balancing of rotating ma	en motorized Gyroscop	tion and Dynamic condition	
	2. 3	Study the pressure distribution in t	he journal bearing	tion and Dynamic condition.	
	4.	Estimate the critical speed of the s	haft with different end	conditions.	
	5.	Analyse the follower displacement	t versus cam rotation ar	igle for different types of cams.	
	6.	Predict the radius of gyration of ro	of gyration of rod by using bi-filler and tri-filler suspension.		
	7.	Estimate the natural frequency of u	un-damped free vibratio	ons of spring –mass system.	
	8.	Analyze the natural frequency of	forced damped and un-	-damped vibration of spring mass	
		system.	*		
	9.	Analyze the natural frequency of t	torsional vibration of si	ingle rotor system using universal	
		vibration test setup.			
	10.	Determine the impact strength of r	naterial using impact te	esting machine	
	11.	Obtain the tensile behaviour of the	e material under UTM.		
Textbooks and	1.	F. P. Beer, E. R. Johnston, J. T.	. Dewolf, and D. Maz	zurek, "Mechanics of Materials",	
References		McGraw Hill, 7thEdition,2014.			
	2.	R. C. Hibbeler, "Mechanics of Ma	terials", Prentice Hall,	8thEdition, 2010.	
	3.	C. Ugural, "Mechanics of Material	ls", Wiley, 1stEdition, 2	2007.	
	4.	J. M. Gere and S. Timoshenko,	"Mechanics of Materi	als", PWS Publishing Company,	
		4thEdition,1997.			

Course Title	Entrepreneurship and Management Functions	tCourse No	MANK301T
Course category	НМС	Structure (IPC)	3-0-3
Offered for	B. Tech All Branches	Status (Core/Elective)	Core
Prerequisite	Engineering Economics	Effective from	July 2019
Course	The aim of this course is to introduce the	ne basic Management fund	ctions to the U.G. students
Objective	which enables them to enter into the corporate environment after graduation. This course also brings in Innovation mind set in to students mind by way of introducing to Entrepreneurship eco system.		
Course Outcomes	 At the end of the course the student will be able to 1. Understand the corporate management skills and entrepreneurship skills 2. Understand the Management functions in an Enterprise environment 3. Carry out Manager and Leadership functions 4. Understand the Innovation and Entrepreneurship 		
Contents of the course (With approximate break up of hours)	 Introduction to Entrepreneurship, Manager vs Entrepreneur, Functions and Characteristics of Entrepreneur, Types of Entrepreneurs, Intrapreneurs, Stages in Entrepreneurship process, Role of Entrepreneurs in Society (6) Indian Economy & Industries, Business Opportunities, Preparation of Business Plan, Institutional Support, Startup Eco system (6) Nature of Management, Development of Management Thought, Approaches to Management, Policy, Procedure, Methods and Rules, Planning, Forecasting, Objectives and MBO (8) Staffing, Performance appraisal, Training & Development, Job analysis & Evaluation, Directing, Motivation, Leadership (6) 		
	Management, Types of Organization, O Supervision, Communication, Controll Ethics, Operation Research, Manageme	brganization Chart and Ma ling, Co-ordination, Man nt Information System (8)	nuals (8)
Textbooks and References	 2. K. R. Phanesh, "Management & Entrepreneurship", Sudha Publications, 2018; 3. A. K. Gupta, "Engineering Management", S. Chand & Company Ltd, 2012. 		

Course Title	Heat Transfer	Course No	ME301T
Course category	PEC	Structure (IPC)	3-0-3
Offered for	B. Tech, MDM	Status (Core/Elective)	Core
Pre-requisite	Thermal Engineering – Concepts & Applications Fluid Mechanics and Hydraulic Machinery	Effective from	July 2019
Course Objective	The objective of this course is to und application in various Engineering system	lerstand the basic modes of stems.	heat transfer and their
Course Outcomes	After completion of the course, students will be able to: 1. Understand the basics of heat transfer and their practical relevance in various simple geometries. 2. Interpret the steady and unsteady state heat transfer scenarios and fins. 3. Apply the relevant expressions to solve free and forced convection problems. 4. Apply the concepts of heat transfer in boiling, condensation and radiation thermal systems. 5. Design the heat exchanger for engineering applications		
Contents of the Course (With approximate break up of hours)	Basics: Basic modes and Applications of heat transfer. (2) k Conduction: General heat conduction equation, Initial and boundary conditions, One dimensional steady state conduction in plane and composite systems, Electrical analogy, Systems with variable thermal conductivity, heat generation, Critical radius of insulation, Analysis of Extended surfaces, One dimensional transient conduction. (15) Convection: Dimensional analysis, concept of boundary layer, Forced convection in external and internal flows, natural convection in external flows, heat transfer phenomena in boiling and condensation. (12) Thermal Radiation: Nature of radiation, Concept of Black and Non-black bodies, Laws of Black Body Radiation, Radiation heat exchange between surfaces, Radiation shields. (6) Heat exchangers: Classification, flow arrangement, Overall heat transfer coefficient,		
Textbooks and References	 J. P. Holman and Souvik Bhattacha 2011. Incropera, Dewitt, Bergmann, Law Wiley, 6th edition, 2010. Frank Kreith, Mark S. Bohn, Raj Learning Custom Publishing; 7th Inte 4. M. Necati Ozisik, "Heat Transfer- 5. C. P. Kothandaraman and Subrama Age International Publications, 8th Ec 	aryya, "Heat Transfer", McG vine, "Fundamentals of Hea Manglik, "Principles of He rnational student edition, 20 A basic Approach",4th Editio nian, "Heat and Mass Transf lition, 2012.	Fraw Hill, 10th edition, t and Mass Transfer", at Transfer", Cengage 10. on, McGraw, 1985. Fer Data Book", New

Course Title	Automation in Manufacturing	Course No	ME302T	
Course category	PEC	Structure (IPC)	3-0-3	
Offered for	B.Tech, MDM	Status (Core/Elective)	Core	
Prerequisite	Nil	Effective from	July 2019	
Course Objective	The objective of this course is to learn to various mechatronic and automation de the contribution of hydraulic, pneumati systems will be studied.	bjective of this course is to learn the techniques and methodologies of integrating s mechatronic and automation devices in manufacturing systems. In particular, ntribution of hydraulic, pneumatic, robotic systems and PLCs in manufacturing as will be studied.		
Course Outcomes	 At the end of the course, a student will be able to: 1. Integrate various electro-mechanical devices in manufacturing. 2. Develop pneumatic and hydraulic circuits for manufacturing applications. 3. Automate a manufacturing system with various sensors, actuators and controllers. 4. Understand the concepts of Robotics in Automation. 			
Contents of the course (With approximate break up of hours)	Mechatronic Systems: Overview of mechatronic systems and devices in manufacturing, automated feeding, transfer, retrieval mechanisms and devices, AGVs, FMS workstations, material handling and storage systems, overview of sensors, transducers and control systems in manufacturing. (6)			
	Hydraulic Systems: Hydraulic systems: flow, pressure and direction control valves actuators, supporting and control elements, pumps, servo valves and actuators, electron hydraulic servo- valves, proportional valves and their applications, design of hydraulic circuits for manufacturing applications and performance analysis. (10) Pneumatic Systems: Production, distribution and conditioning of compressed air system components and graphic representations, design of circuits-switching circuit and sequential circuits, cascade methods, step counter method, compound circuit design. (10)			
	Robotics in Automation: Robot classification and anatomy, forward and inverse kinematics, DH matrix transformation, Jacobian and differential motion, Trajectory planning, Static and dynamic analysis, applications in manufacturing. (12) PLCs and Microprocessors: Basic structure - Input / Output processing - Programmin			
	output - Selection of PLC, Program manufacturing applications. (6)	Anemonics Timers, Internal relays and counters - Data handling - Analog input iput - Selection of PLC, Programming and interfacing of microprocessors i inufacturing applications. (6)		
Textbooks and References	 Anthony Esposito, "Fluid power with M P. Groover, "Industrial Robotics: McGraw- Hill, 2ndEdition, 2012. K. S. Fu, "Robotics: control, sensing Bolton, W., "Mechatronics: electron engineering", McGraw Hill,2009. DebS.R., "Robotics technology and Hill, 2009. Boucher, T. O., "Computer auton Chapman and Hall, 1996. Morris A. Cohen and Uday M. Aptu 1997. 	Anthony Esposito, "Fluid power with applications", 7 th Edition, PrenticeHall, 2008. M P. Groover, "Industrial Robotics: Technology, Programming and Applications", McGraw- Hill, 2 nd Edition, 2012. K. S. Fu, "Robotics: control, sensing, vision and intelligence", Mcgraw-Hill, 1987. Bolton, W., "Mechatronics: electronic control systems in mechanical and electrical engineering", McGraw Hill, 2009. DebS.R., "Robotics technology and flexible automation", 2 nd Edition, Mc Graw Hill, 2009. Boucher, T. O., "Computer automation in manufacturing - an Introduction", Chapman and Hall, 1996. Morris A. Cohen and Uday M. Apte, "Manufacturing Automation", McGraw Hill, 1997.		

Course Title	Manufacturing Automation Practice	Course No	ME302P	
Course category	PEC	Structure (IPC)	0-3-2	
Offered for	B Tech MDM	Status (Core/Elective)	Core	
Pre-requisite	Nil	Effective from	July 2019	
Course Objective	To acquire hands on experience in integrating various mechatronic and automation devices such as hydraulic, pneumatic, robotic systems, PLCs and computers in manufacturing systems.			
Course	At the end of the course, a student will	At the end of the course, a student will be able to:		
Outcome	 Integrate various electro-mechanical devices in manufacturing. Develop pneumatic and hydraulic circuits for manufacturing applications. Automate a manufacturing system with various sensors, actuators, robot mechanisms, PLCs and other controllers. 			
Contents of the	The following experiments are conduc	ted:		
course	 Integration of various sensors manufacturing applications. Identification of faulty components Computer based design and simular Operational component and implification of the given manufacturing processing for the given manufacturing processing and integration automation. Programming and integration manufacturing. Design and development of schemes in manufacturing automation 	s, actuators and other ments, orientation errors, a mulation of automated ma ementation of pneumation of pneumation of robot mechanism of PLCs and commicroprocessor and committee com	mechatronic devices in ssembly errors etc. nufacturing systems. c and hydraulic circuits ms in manufacturing trol of equipment in computer-based control	
Textbooks and	1. Anthony Esposito, "Fluid power w	vith applications", 7 th Editio	n, PrenticeHall, 2008.	
References	 M P. Groover, "Industrial Robo McGraw- Hill, 2ndEdition, 2012. K. S. Fu, "Robotics: control, sensite Bolton, W., "Mechatronics: elect 	tics: Technology, Program ng, vision and intelligence' ronic control systems in	mming and Applications", ,Mcgraw-Hill,1987. mechanical and electrical	
	engineering", McGraw Hill.2009.			

Course Title	Machine Tool Technology	Course Number	ME303T	
Course category	PEC	Structure (IPC)	3-0-3	
Offered to	B.Tech, MDM	Status (Core/Elective)	Elective	
Prerequisite	Basic Concepts in Manufacturing	Effective from	July 2019	
	Process			
Course Objective	The objective of this course is to dev	elop competency in under	standing of machine	
	tools and its working principles.			
Course Outcomes	At the end of the course, the students will be able to:			
	1. Understand the design considerations for special features in Machine tools.			
	2. Apply the knowledge of various mad 3. Design ligs and Fixtures for work ar	d tool holding in machinin	g of a product.	
Contents of the course	5. Design Jigs and Fixtures for working a	and specification of lathe	g a given product. Types of lathes	
Contents of the course	Work holders and tool holders _I at	the accessories. Operation	- Types of Talles -	
(With approximate	turning-Thread turning and lathe attach	ments. (8)	is on Lame raper	
break up of hours)				
	Turret and Capstan Lathes: Principle of	t working -Collet chucks –	Other work and tool	
	noiding devices – Box and tool layout.	(4)		
	Shaping, Slotting and Planing Machin	nes: Principles of working	; – Principal parts –	
	Specification, classification, operations	s performed, machining tim	e calculations. (6)	
	Drilling and Boring Machines: Princip	les of working, specificatio	ons, types, operations	
	performed – tool holding devices – twist drill – Boring machines – Fine boring			
	machines – Jig Boring machine. Deep hole drilling machine. (6)			
	Milling Machines: Principle of working – Specifications – Classifications of milling			
	machines – Principal features of horizontal, vertical and universal milling machines –			
	Machining operations-Types -Geometr	y of milling cutters –Millin	ng cutters – Methods	
	of indexing – Accessories to milling machines. (6)			
	Grinding Machines – Fundamentals – Theory of grinding –Classification of grinding			
	machine – Cylindrical and surface g	grinding machine – Tool	and cutter grinding	
	machine – special types of grinding ma	ine – special types of grinding machines. (6)		
	Lapping, Honing and Broaching Machines: Comparison to grinding – lapping and			
	honing. Constructional features of spe	ed and feed units, machinin	ng time calculations.	
	(6)		•	
	ligs and Fixtures. Principles of design	of ligs and fixtures and up	ses Classification of	
	ligs & Fixtures – Principles of location	on and clamping $-$ Types (of clamping & work	
	holding devices. Typical examples of j	igs and fixtures. (6)	or champing a work	
Taythooks and	1 C.C. Son and A. Phattachamia "Pri	incinias of machine Teels"	Now Control Pool	
References and	A gency	incipies of machine roots	, New Central Book	
References	2 G Boothroyd and W A Knight "F	undamentals of machining	and machine tools"	
	3 rd Edition, Taylor & Francis.			
	3. D. K Pal and S. K. Basu, "Design of Machine Tool". 4th Edition. Oxford &			
	Publishing Pvt. Ltd.	,		
	4. G.E. Dieter, "Engineering Design:A	Materials and processing	approach", McGraw	
	Hill, 1991.			

Course Title	Design of Machine Elements	Course No	ME304T	
Course category	PEC	Structure (IPC)	3-0-3	
Offered for	B.Tech, MDM	Status (Core/Elective)	Core	
Prerequisite	Engineering Mechanics Mechanics of Materials	Effective from	July 2019	
Course Objective	The objective of this course is to introduce design concepts and procedures necessary to design and/or select a machine component in terms of geometry and materials			
Course Outcomes	 At the end of the course, a student will be able to 1. Analyze the stresses in machine elements and structural members under various loads 2. Apply multidimensional failure criteria in the analysis and design of machine components 3. Design various joints in Machine components. 4. Design power transmission systems involving belts and chains 5. Determine the fatigue life of shafts, gears and bearings under varying loads Design philosophy, revision of failure theories, limits, fits and design under static load (4) 			
Contents of the Course (With approximate break up of hours)	Design of riveted, bolted and welded joints and Power Screws. (10) Design and selection of belt drives. (4)			
	Design of Gears: spur and worm gears, Contact and bending fatigue strength, accuracy. (8) Tribology: Lubricant theories; Design of Journal bearings; Selection of ball and bearings (6)			
Textbooks and References	 V Bhandari, 'Design of Ma Edition, 2010. R G Budynas, K J Nisbett, ' 10th Edition, 2014 R L Norton, 'Machine Design' C S Sharma and K Purohit, 'D P C Gope, 'Machine Design: India, 2011 	Achine Elements', McC Mechanical Engineerin ', Prentice Hall, 5th Edit Pesign of Machine Elemony : Fundamentals and Ap	Graw-Hill Education, 3rd ng Design', McGraw Hill, tion, 2013 ents', Prentice Hall, 2008 oplications', Prentice Hall	

Course Title	Microprocessors and Controllers	Course No	ME305I	
Course category	PEC	Structure (IPC)	1-3-3	
Offered for	B.Tech, MDM	Status (Core/Elective)	Core	
Pre-requisite	Nil	Effective from	July 2019	
Course Objective	To develop good understand microprocessor/microcontrollers, ga programming techniques with micr practically the concepts of per microcontrollers	ing of operating in comprehension and roprocessors and micro ipherals interfacing w	principles/architecture of hands on experience of controllers and also learn vith microprocessors and	
Course Outcomes	 At the end of the course, a student will be able to: 1. Understand the concepts of binary and hexa-decimal number systems 2. Familiarize with the architecture of 8085 Microprocessor. 3. Program the microprocessors/microcontrollers for solving practical problems 4. Interface memory/keyboard/display etc. with microprocessors/micro controllers and run the devices like stepper meters ato 			
Contents of the course (With approximate break up of hours)	Binary and Hexadecimal number operations, Logic gates, Addition, multiplexor, and concept of memory	systems and conversio Subtraction, encoder,	n, Arithmetic and logical decoder, multiplexor, de-	
	Architecture and Programming of 8085 Microprocessor. Interfacing of 8085 with memory and input /output ports, hex keyboards etc.,			
	Introduction – Standalone computers versus computers as components – Examples of Embedded computing systems. Elements of embedded controllers such as A/D converters, PWM circuits and timers			
	Introduction to the 8051 microcontrollers programming and interfacing with A/D, D/A converters, Sensor interfacing and signals conditioning.			
Textbooks and	1. M. MorrisMano, "DigitalLogicar	ndComputerDesign",1st I	Edition, Pearson, 2013.	
References	 R. Gaonkar, "Microprocessor Ar 8085", 6th Edition, Penram,2013 M.A. Mazidi, J.G. Mazidi and Systems", 2nd Edition, Pearson E Kenneth J.Ayala, "The 8051 1 Learning. Douglas V. Hall, "Microprocess 	chitecture, Programming R.D. Mc Kinlay, "Mich Education, 2009. Mocro-controller", 3rd	g, and Applications with the rocontroller and Embedded edition, Thomson Delmar	
	2nd edition, McGraw-Hill, 1990.	ons and mornaonig. The	Summing and mateware,	

Course Title	Fluid Mechanics and Heat Transfer Practice	Course No	ME306P
Course category	PEC	Structure (IPC)	0-3-2
Offered for	B.Tech, MDM	Status (Core/Elective)	Core
Pre-requisite	Fluid Mechanics and Hydraulic Machinery	Effective from	July 2019
Course Objective	The objective of this course is to familiarize the students with fluid mechanics and heat transfer equipment.		
Course Outcomes	 At the end of this course, the student will be able to: 1. Compute the different losses in pipe flows. 2. Estimate the thermal conductivity of different materials, and Fin performance parameters. 3. Evaluate the free and forced convection heat transfer coefficients. 4. Determine the overall heat transfer coefficient of the Drop and Film wise condensation. 		
Contents of the	The following Experiments are designed to:		
course	 Estimate the major and minor losses in a flow through pipe. Study of linear and radial heat transfer conduction using Fourier's Law. Measurement of thermal conductivity of non-metallic material under steady state experiments. Estimate the Effectiveness and efficiency of the pin fin apparatus under forced condition. Determine the overall heat transfer coefficient of both the Drop and Film wise condensation. Estimate the Heat Transfer coefficient of both Natural and forced convective system 		
Textbooks and References	 J. P. Holman and Souvik Bhattacharyya, 2011. Incropera, Dewitt, Bergmann, Lavine, "Wiley, 6th edition, 2010. Robert W. Fox, Philip Journal Pritchard and Mechanics", 8th Edition, Wiley India Pvt. Ltd 	"Heat Transfer", McGraw Fundamentals of Heat an nd Alan T. McDonald, "In I.,2013.	Hill, 10th edition, d Mass Transfer", troduction to Fluid

Course Title	Design for Quality and Reliability	Course No	DES302T		
Course category	DES	Structure (IPC)	3-0-3		
Offered for	B. Tech All Branches	Status (Core/Elective)	Core		
Prerequisite	Nil	Effective from	July 2019		
Course Objective	The objectives of the course are to help engineering students understand the concepts o quality & reliability and also evaluate the overall reliability of a system from component reliability.				
Course	Attending the course would enable the student to:				
Outcomes	 Model repairable and non-repairable systems and calculate failure rate ,repair rate, reliability and availability Use various probability density distributions significant to reliability calculations. Fit a given failure data set of a product in to a Weibull distribution and estimate the middle bilter approachem. 				
Contents of the	Concepts of Product Quality Quality	v Function Deployment	/ House of Quality SixSigma		
Course	(8)	y runction Deployment	House of Quanty, Shabigina		
(With approximate					
break up of hours)	Concepts of Reliability, Basic concepts of repairable and non-repairable systems, Reliability, Availability and Maintainability (8)				
	Failure data analysis, Fitting discrete and continuous distributions to failure data sets, Weibull analysis, estimation of important reliability parameters (10)				
	Calculation of System Reliability from Component reliabilities, Markov modeling of repairable and non-repairable systems, Reliability Logic Diagrams, Fault-tree analysis (10)				
	Preventive and Predictive maintenance, Failure Modes and Effects Analysis. (6)				
Textbooks and References	 Louis Cohen, Joseph P. Ficalora, Handbook", Second Edition, Pren V. N. A.Naikan, "Reliability Engi SingiresuS. Rao, "Reliability Eng Patrick O Connor, "Practical Reliability Enginerics" 	"Quality Function Deplo tice Hall, 2009. ineering and Life Testing ineering", PearsonEducar ability Engineering", Joh	yment and Six Sigma: A QFD ", PHI Learning, 2010. tion,2014. n Wiley,2009.		
	5. B.L. Hansen and P.M. Ghare, "Ou	ality Control and Applic	ations", Prentice Hall, 1997.		

Course Title	Computational Methods in Engineering	Course No	ME307T	
Course category	PEC	Structure (IPC)	3-0-3	
Offered for	B.Tech, MDM	Status (Core/Elective)	Core	
Pre-requisite	Engineering Mechanics, Fluid Mechanics, Heat Transfer, Mechanics of Materials	Effective from	July 2019	
Course Objective	The objective of this course is to provide the fundamentals of finite element and finite difference methods, and modeling assumptions to solve structural and heat transfer problems.			
Course Outcomes	At the end of the course, a student will be able to 1. Understand the importance of obtaining approximate solutions to various practical problems 2. Model machine elements and structures, and analyze the stresses and strains 3. Analyze the heat transfer problems			
Contents of the course(With	Fluid flow & Heat Transfer: Difference consistency and stability. (6)	representation of Pl	DEs including errors,	
approximate break up of hours)	Application of Numerical Methods to Heat equation, Laplace's equation and Burgers'equation. Application of Finite Volume Formulation to One-dimensional Steady diffusion.(12)			
	Boundary value problems - Classical solution methods: Weighted residual techniques and Rayleigh-Ritz method. (9)			
	Finite Element Method: Discretization, shape functions, boundary conditions, element stiffness matrix, assembly technique for global matrices - Numerical integration - Application to trusses, beams and heat transfer problems. Tutorials. (15)			
Textbooks and References	1.Richard H. Pletcher, John C. Tannehill, Dale Anderson, "Computational Fluid Mechanics and Heat Transfer", Third Edition (Series in Computational and Physical Processes in Mechanics and Thermal Sciences), CRC Press, 2012.			
	2. T R Chandrupatla and A D Belegundu, 'Introduction to Finite Elements in Engineering', 3rd Edition, PHI Learning, 2009			
	3. J N Reddy, 'An Introduction to the Finite Element Method', McGraw-Hill Education, 3 rd Edition, 2005			
	4. Patankar, S.V., Numerical Heat Transfer and Fluid Flow, McGraw-Hill, 1980.			
	5. Muralidhar, K., Sundarajan T., "Computational Fluid Flow and Heat Transfer", NarosaPublishing House, New Delhi, 1995.			
	6. Versteeg Henk Kaarle, MalalasekeraWeeratunge, "An introduction to computational fluiddynamics: The finite volume method", Pearson Education, 2007.			
	7. Seshu P., "Finite Element Analysis", Pren	tice Hall India, 2003.		
	8. JacobFish and Ted Belytschko, "A first Course in Finite Elements", John Wily & Sons,2007			

Course Title	Mechanical Design Simulation Practice	Course No	ME307P
Course category	Mechanical Engineering	Structure (IPC)	0-3-2
Offered for	B.Tech, MDM	Status (Core/Elective)	Core
Pre-requisite	Heat Transfer Mechanics of Materials	Effective from	July 2029
Course Objective	To make acquainted the students using computer aided engineering tools to design and analyze the structural, fluid flow and heat transfer related systems.		
Course Outcomes	 At the end of the course, a student will be able to: 1. Draw 1D, 2D and 3D Finite Element Models of mechanical systems. 2. Understand the solution techniques available in computer-aided engineering tools. 3. Evaluate the design of mechanical systems by conducting stress analysis, thermal analysis or fluid flow analysis. 		
Contents of the course	tents of the Creation of Finite Element Models and Evaluation of Displacements, Stress Reaction Forces of axially and transversely loaded members, thin plates or disc pipes or dams, and brackets using Static Structural Analysis.		
	Evaluation of natural frequencies and me members using Dynamic Structural Analys	ode shapes of axially and is.	d transversely loaded
Construction of Finite Element Models and study of temperation composite plane walls and chimneys or other plane sections using the section of the section o			distribution in fins or ermal Analysis.
	Building of Finite Element Models and study of velocity distribution of fluid in channel or pipes over bluff bodies using steady state fluid flow analysis.		
Textbooks and References	 Saeed Moaveni, "Finite Element Analysis: Theory and Application with ANSYS' Pearson, 2011. Tirupathi R. Chandrupatla and Ashok D. Belegundu, "Introduction to Finite Elements in Engineering", Prentice Hall of India,2001. Erdogan Madenci and Ibrahim Guven, "The Finite Element Method and Applications in Engineering Using ANSYS", Springer,2015. 		

Course Title	Thermal Energy Systems	Course No	ME308T	
Course category	PEC	Structure (IPC)	3-0-3	
Offered for	B.Tech, MDM	Status (Core/Elective)	Core	
Prerequisite	Thermal Engineering Concepts and Applications	Effective from	July 2019	
Course Objective	The objective this course is to provide an insignergy conversion systems using the concepts	ght of fundamentals and of Thermal Engineering	salient features of major	
Course Outcome	 At the end of the course the student will be able to: 1. Understand the concepts of a Steam power plant. 2. Comprehend the concepts a Gas turbine plant. 3. Acquire the knowledge of the Internal Combustion engine components. 4. Appreciate the concepts of Refrigeration and their applications. 5. Analyze the psychrometric properties and processes used in Air Conditioning systems. Steam power cycles: Steam Power plant and its components, site selection, Carnot Vapo 			
Contents of the course (With	 Power Cycle, Rankine cycle, Rankine Cycle with Reheat, Superheat, and Regeneration, Plant efficiency, Cogeneration. (8) Gas Turbines: Gas turbine plant and its components, Brayton cycle, Classification, Analysis of Closed and Open cycle Gas Turbine plants, Methods of improving performance, Intercooler, Regeneration and Reheating, Applications. (5) 			
up of hours)	Internal Combustion Engines: Basic components and nomenclature, Classification, working principles of 2-stroke & 4-stroke SI and CI, Engines, Air-standard and Real cycles, Fuels, Stoichiometric Air-Fuel ratio, Combustion: Detonation and Knocking, Carburetion, Injection, Ignition and cooling systems, Parameters of performance, Exhaust emissions. (15)			
	Refrigeration: Gas Refrigeration system, Vapour compression cycle, Effect of sub-cooling and superheating, Multistage systems, Cascade systems, Vapour Absorption cycle, Refrigerants (9) Air-conditioning: Psychrometric properties, Psychrometric chart, Psychrometric processes, Components of Air conditioning system, Classification of Air conditioning systems (5)			
Textbooks and References	 T. D. Eastop, A. McConkey, "Applied T 5th Edition, Pearson India,2002. P. K. Nag, "Power Plant Engineering", 4th Wilbert F. Stoecker and J.W. Jones, "Re McGrawHill,2002. John B. Heywood, "Internal Combustion E 5. V. Ganesan, "Internal Combustion Engine. V. Ganesan, "Gas Turbines" – McGrawHi H. I. H. Saravanamuthoo, H. Cohen, G. F Pearson, 2001. 	hermodynamics for Eng Edition, McGraw Hill, 2 efrigeration and Air Co Engine Fundamentals,Mo s", 4th edition, McGraw II, 3 rd Edition, 2010. F. C. Rogers, "Gas Turb	tineering Technologists", 2014. onditioning", 2 nd Edition, cGraw Hill,2011. Hill, 2012. ine Theory", 5 th Edition,	

Course Title	Thermal Engineering Practice	Course No	ME308P	
Course category	PEC	Structure (IPC)	0-3-2	
Offered for	B.Tech, MDM	Status (Core/Elective)	Core	
Pre-requisite	Heat Transfer	Effective from	July 2019	
Course Objective	The objective of this course is to imb systems	ibe the practical knowledge i	n various modern thermal	
Course	At the end of the course, the student w	t the end of the course, the student will be able to:		
Outcome	1. Estimate the heat transfer coefficie	1. Estimate the heat transfer coefficients of various heat exchangers.		
	2. Study the performances of Solar P	V Trainer kit and Wind energ	gy trainer kit.	
	3. Familiarize the students with Refri	geration and Air-Conditioner	test rigs.	
	4. Familiarize the students with IC en	igines.		
Contents of the	The following experiments are	conducted to:		
course	 Find out the COP of a Refrigeration Estimate the COP of Air Condition Determine the overall heat transformation Determine LMTD, effectiveness counter flow heat exchanger for construction Understand relationship of heat the geometry. Study the performance of Petrol II Study the performance of Wind environment 	ion Test rig at various loading oner Test rig at various loading er coefficient and dirt coeffic er coefficient and film coeffic and overall heat transfer coef concentric tube flow. ransfer and flow regime in a p Engine PV Trainer kit.	g conditions. ng conditions. ient of the given shell cient for jacketed vessel ficient for parallel and plate heat exchanger	
Textbooks and References	 J. P. Holman and Souvik Bhatt Hill, 2011. V. Ganesan, "Internal Combus Wilbert F. Stoecker and J.W 2ndEdition, McGraw Hill, 200 P. K. Nag, "Power Plant Engin 	tacharyya, "Heat Transfer" tion Engines", 4th edition, 7. Jones, "Refrigeration a 92. neering", 4th Edition, McG	, 10th edition, McGraw McGraw Hill, 2012. and Air Conditioning", raw Hill, 2014.	

Course Title	Product Design Practice	Course No	INT303	
Course category	DES	Structure (IPC)	0-3-2	
Offered for	B.Tech All Branches	Status (Core/Elective)	Core	
Prerequisite	Design Realization Practice, Product Realization Practice	Effective from	July 2019	
Course Objective	Students will develop cross-discipline p realization tools in a multi- disciplinary team	roducts and prototype n setting.	them using product	
Course Outcomes	 By the end of the course, the students would be able to: 1. Develop cross disciplinary idea 2. Conceive, design and prototype an innovative idea 3. Work in cross-functional groups and to apply the concepts learnt in theory to a practical problem 4. Manage group projects, maintain timeliness and follow method-oriented approach to problem solving 			
Details about the course	This course is an inter-disciplinary team based product design and prototyping course. The concept of the course is to provide hands on learning experience in interdisciplinary fields of engineering and exposure to the context of a "real" product design problems. In this course students will design a product by following the systematic product design process.			
	A team consist of students from different discipline will choose their own innovative product and while designing, students will consider many issues like market opportunities, formal requirements and constraints, the environment in which the product will be used, product look and feel; technical legitimacy, and manufacturing considerations for the products.			
	During the course, students will learn and put in to practice team working, project management and product realization practices commonly found in product developers in industry. Throughout the semester, the student teams have several opportunities to present their progress to their fellow students and faculty.			
Textbooks and References	 Carl Liu, "Innovative Product Design Pr Bjarki Hallgrimsson, "Prototyping and King Publishing Limited, 2012. 	actice", Kindle Edition, A Modelmaking for Produ	ASIN:B00B29V9RQ uct Design", Laurance	

Course Title	Mechanical Vibrations	Course Number	ME501T
Course category	PEC	Structure (IPC)	3-0-3
Offered to	B.Tech, MDM	Status (Core/ Elective)	Elective
Prerequisite	Dynamics of Machines	Effective from	July 2019
Course Objective	The objective of this course is to learn the	ne fundamentals of vibration	on theory and model
	real world mechanical vibration problems.		
Course Outcome	At the end of this course, the student will l	be able to:	
	1. Understand the free and forced vibration	on of single, two and mult	ti degree of freedom
	systems.		
	2. Understand the working principle of vib	bration measuring instrume	nts
	3. Mathematically model vibration problem	ns and to mitigate vibration	1 effects
	4. Design and develop vibration absorbers, dampers and vibration isolators		
Contents of the	Introduction to vibration and its affects	s such as shart, fou and bea	ulls.
course	freedom continuous systems and discrete	systems (4)	systems, degrees of
(With approximate	needoni, continuous systems and discrete	systems.(+)	
break up of hours)	Single Degree of Freedom System	s- formulation. energy me	thod. Newton -Euler
	method, Free vibration, Un-damped an	d damped free vibration	on, Forced vibration,
	harmonic excitation, solution of diffe	rential equation of motion	n, Vector approach,
	Complex frequency response, Magnification factor Resonance, Rotating/reciprocating		
	unbalances, Force Transmissibility, Motion Transmissibility, Vehicular suspension,		
	Vibration measuring instruments, Case studies on forced vibration.(10)		
	Two Degree of Freedom Systems: Free	and forced vibration of li	near systems, Eigen
	values and Eigen vectors, Normal mode	s and mode superposition,	Application to two
	degree of freedom systems. (10)	* *	**
	Multi deeree of fundem systems, Introduction, Fermulation of existing of multi-		
	Multi degree of freedom systems: Introduction, Formulation of equations of motion, Free		
	vibration response, Natural modes and i	mode shapes, Orthogonall	y of model vectors,
	normalization of model vectors, mode su	per position, Forced vibrat	ion analysis through
	model analysis, Model damping, Rayle	eign's damping, introducti	ion to experimental
	model analysis.(10)		
	Continuous Systems: Vibration of strings	rod shaft beams and mem	branes (8)
Textbooks and	1. W. T. Thomson, M. D. Dahleh and	C. Padmanabhan. "Theor	v of Vibrations with
References	Applications", 5th edition, Pearson Ed	lucation, 2008.	j or vioradionis vitar
	2. S. S. Rao, "Mechanical Vibrations"	, 6 th Edition, PearsonEduca	tion, 2017.
	3. L. Meirovitch, "Fundamentals of Vibr	ations", Waveland Pr Inc, 2	2010.
	4. C. Sujatha, "Vibration and Acoustics"	, 1st edition, Tata McGraw	Hill, 2010.
	5. Preumont, "Vibration Control of Act	tive Structures-An Introdu	ction", Springer, 3 rd
	Edition, 2011.		
	6. A.K. Mallik and S. Chatterjee, "Princ	ciples of Passive and Active	e Vibration Control",
	1 st Edition, Affiliated East West Press,	2014.	0.0 1000
	7. D. J. Mead, "Passive Vibration Contr	ol", 1st edition, John Wiley	v & Sons, 1998.

Course Title	Advanced Solid Mechanics	Course Number	ME502T
Course category	PEC	Structure (IPC)	3-0-3
Offered to	B.Tech, MDM	Status (Core/ Elective)	Elective
Prerequisite	Mechanics of Materials	Effective from	July 2019
Course Objective	The objective of the course is to provid	le the advanced analysis	techniques for the
	boundary value problems in solid structur	es.	
Course Outcomes	At the end of the course, the student will	be able to:	
	1. Apply the stress-strain relations for linearly elastic members using normal stress,		
	shear stress and distortion energy the	ories.	
	2. Analyse the mechanical structures usi	ng energy methods.	
	3. Design straight beams, curved and as	ymmetrical bending of bea	ms
	4. Analyse the beams under unsymmetri	cal loading.	
	5. Apply shear centre of thin wall beams	s, torsion & axisymmetric	problems
Contents of the course	Analysis of Stress – Traction vector, stress tensor, Principle stresses, Hydrostatic and		
(With approximate	deviatoric stresses Analysis of Strain – displacement field, deformation tensor, strain		
break up of hours)	tensor, principle strain (14)		
	Stress-Strain Relations for Linearly Elastic Solids-Anisotropic, isotropic behaviour (6) Theories of Failure: Significance of the theories of failure, Factor of safety in design.		
	(5)		
	Energy Methods: Hooke's law and the principle of superposition, Work done by forces and elastic strain energy stored, Reciprocal theorem, First theorem of Castigliano, Theorem of virtual work. (5)		
	Bending of Beams: Straight beams and asymmetrical bending, Bending of curved beams. (6)		
	Torsion & Axisymmetric Problems: Torsional of general prismatic bars-solid sections, Stresses in composite tubes, Thermal Stresses. (6)		
Textbooks and References	 Irving H. Shames, "Mechanics of Def L.S. Srinath, "Advanced Mechanics of 	formable Solids", Krieger I of Solids", 3rd Edition,TMI	Pub Co, 2008. H, 2009.

Course Title	Computer Aided Design and Manufac	cturing Course No	ME503T
Course category	PEC	Structure (IPC)	3-0-3
Offered for	B.Tech, MDM	Status (Core/Elective	e)Core
Pre-requisite	Engineering Graphics	Effective from	July 2019
Course Objective	The objective of this course is to pro- design and manufacturing through geo	ovide the fundamental concometric modeling and their i	epts of computer aided representations.
Course Outcomes	 At the end of the course, a student wil 1. Understand the hardware and soft 2. Formulate the mathematical equasurfaces. 3. Understand 3D-solid representation 4. Develop CNC programs for mach 	I be able to: ware requirements of CAD/ ations for geometrical entit on techniques ining complex geometries	CAM. ies such as curves, and
Contents of the	Overview of CAD/CAM: Hardwa	are and software require	ments in CAD/CAM,
course(With approximate break up of hours)	Introduction to geometric representation- Implicit, explicit, parametric equations, Transformations in 2D and 3D projections (8)		
	Parametric curves: Differential geom and geometric form, Blending function Hermite curves, continuity aspects, B de Casteljau algorithm, continuity as open and non- uniform knot vector NURBS curve(8)	netry of curves, Cubic Hern ons, subdivision, re-paramet ezier curves - control polyg spects, rational Beziers, B-s ors and corresponding cur	nite curves - Algebraic erization and composite ons and Bernstein basis, pline curves - periodic, ves, rational B-splines,
	Parametric surfaces: Hermite surface reparameterization, continuity of sur continuity aspects, rational Bezier su uniform knot vectors and correspondi	e - algebraic and geometric faces, Bezier surface - con rfaces, B-Spline surfaces - ng surfaces, rational B-splin	e form, subdivision and ntrol net representation, periodic, open and non- es, NURBS surface(8)
	Representation of solids: Topology of representations - Quadtree, Octree Constructive Solid Geometry (CSG classification, Union, Difference and T	of surfaces, Euler and modi , Halfspace, Boundary R G), Boolean operations in Intersection (8)	fied form of equations, epresentation (B-Rep), 2D - set membership
	Data exchange in CAD/CAM: CN geometry, CNC Program generation file formats for data exchange, Intereverse engineering, Rapid prototypin	C part programming for from CAD models, Concep erfacing with manufacturing g, Computer aided process	ordinary and complex ts of native and neutral g systems, Concepts of planning (10)
Textbooks and References	 Zeid. I, "CAD/CAM Theory and 2 Rogers, D.F and Adams, Graphics",McGraw Hill, 2002. Chee Kai Chua,Kah Fai Leong,Cl 2010. Rogers. D.F, "An Introduction to 5. J. Hoschekand D. Lasser, "Compu- 6. MortensonM.E, "GeometricMode 7. Gerald E. Farin, "Curves and Surf. 	Practice", Tata McGraw Hill J.A, "Mathematical Ele hu Sing Lim, "Rapid prototy NURBS", Morgan Kaufman uterAidedGeometricDesign' eling", JohnWiley, 1985. faces for CAGD", Morgan F	, 2006. ments for Computer yping",World Scientific, m,2001. ',AKPeters,1996. Kaufmann,2002.

Course Title	Modern Manufacturing Technology	Course Number	ME504T
Course category	PEC	Structure (IPC)	3-0-3
Offered to	B.Tech, MDM	Status (Core/Elective)	Elective
Prerequisite	Basic Concepts in Manufacturing Process	Effective from	July 2019
Course Objective	To inculcate specialized knowledge a using the principles and methods of eng	nd skill in advanced man	ufacturing processes
Course Outcomes	 At the end of the course, the students will be able to: 1.Model the material removal in various modern manufacturing processes. 2. Analyze the processes and evaluate the role of each process parameter during machining of various advanced materials. 4. Select the best process out of the available various advanced manufacturing processes for the given job assignment. 5. Understand requirements to achieve maximum material removal rate and best quality of machined surface while machining various industrial engineering materials. 		
(With approximate break up of hours)	 Electro Discharge Machining (EDM), Processes mechanism of material removal, parameters effects EDM &application, Electrical Discharge Grinding(EDG), Electrochemical Machining (ECM)Processes, Mechanism of material removal, Tool design, Parameters affecting ECM, Applications, Electro-Chemical Honing(ECH), Electrochemical Deburring (ECD), Electrochemical Grinding(ECG), Electrochemical Discharge Grinding (ECDG), Chemical Machining.(15) Ultrasonic Machining (USM), Cutting Tool System Design, Mechanism of cutting, Parameters affects USM applications. Abrasive Jet Machining (AJM), Variables of AJM, Nozzle Design, Laser Beam Machining (LBM), Thermal and Non-thermal analysis, and applications, Electron – Beam Machining (EBM) and its mechanism, Applications, Plasma Arc Machining (PAM), Equipment, Arc transfer mechanism, Metallurgical efforts, Safety precautions and applications, Plasma are surfacing and plasma Arc Springing, Iron Beam Machining (IBM) and water Jet Machining (WJM). (13) 		
	Modern Forming Processes: Measurement of stress and strain under high strain rate, principles of drop forg operation cam plastometer and mushrooming of billets, formability criteria, explo forming, electro hydraulic forming, magnetic pulse forming, pneumatic mechan high velocity forming, comparison with conventional process, introduction to kin forming, explosive welding. (14)		
References and	 Pandey, P.C. and Shan H.S., "Mode 2004. D. Fishlock and K. W. Hards, "N Newnes Ltd., 1965 	ern Machining Processes", New ways of working wi	th metals" –Geroge
	3."HMT - Production Technology", Ta4. "ASME -High velocity forming of m	ta McGraw Hill, 2004, 198 netals", PHI Publishers.	0.

Course category PEC Structure (IPC) 3-0-3 Offered to B.Tech, MDM Status (Core/Elective) Elective Prerequisite Linear Algebra Effective from July 2019 Course Objective The objective of this course is to introduce the concepts of formulating an engineering problem into a mathematical model to develop an optimal solution. Course Outcomes Course Outcomes After completion of the course student will be able to: Apply linear programming approach for optimizing the objectives of industrial oriented problems. Formulate and solve Transportation Models and assignment Models Implement the strategies in competitive situations and Identify the replacement period of the equipment. Analyze the waiting situations in an organization. Determine the optimum inventory level and resolve the complex problem into simple problems by dynamic programming approach and apply optimum strategies. Contents of the course (With approximate break up of hours) Introduction to Operations Research, operations research models, applications. (2) Linear programming: Formulation, Graphical solution, Simplex method, artificial variables techniques, Two-phase method, Big-M method, Duality Principle. (7) Transportation problem, Degeneracy, Variants of Assignment Problem-Traveling Salesman problem. (7) Game theory: Minimax (maximin) Criterion and optimal solution, unbalanced transporta
Offered to B.Tech, MDM Status (Core/Elective) Elective Prerequisite Linear Algebra Erfective from July 2019 Course Objective The objective of this course is to introduce the concepts of formulating an engineering problem into a mathematical model to develop an optimal solution. Image: Course outcomes Course Outcomes After completion of the course student will be able to: 1. Apply linear programming approach for optimizing the objectives of industrial oriented problems. 2. Formulate and solve Transportation Models and assignment Models 3. Implement the strategies in competitive situations and Identify the replacement period of the equipment. 4. Analyze the waiting situations in an organization. 5. Determine the optimum inventory level and resolve the complex problem into simple problems by dynamic programming approach and apply optimum strategies. Contents of the course Introduction to Operations Research, operations research models, applications. (2) Linear programming: Formulation, Graphical solution, Simplex method, artificial variables techniques, Two-phase method, Big-M method, Duality Principle. (7) Transportation problem, Degeneracy, Variants of Assignment Problem-Traveling Salesman problem. (7) Game theory: Minimax (maximi) Criterion and optimal strategy, Solution of games with saddle points, Rectangular games without saddle points, 2 X 2 games – dominance principle – m X 2 & 2 X n games and graphical method. Theory of replacement: Introduction, Replacement of Equipme
PrerequisiteLinear AlgebraEffective fromJuly 2019Course ObjectiveThe objective of this course is to introduce the concepts of formulating an engineering problem into a mathematical model to develop an optimal solution.Course OutcomesAfter completion of the course student will be able to: 1. Apply linear programming approach for optimizing the objectives of industrial oriented problems. 2. Formulate and solve Transportation Models and assignment Models 3. Implement the strategies in competitive situations and Identify the replacement period of the equipment. 4. Analyze the waiting situations in an organization. 5. Determine the optimum inventory level and resolve the complex problem into simple problems by dynamic programming approach and apply optimum strategies.Contents of the course (With approximate break up of hours)Introduction to Operations Research, operations research models, applications. (2) Linear programming: Formulation, Graphical solution, Simplex method, artificial variables techniques, Two-phase method, Big-M method, Duality Principle. (7) Transportation and Assignment problems: Formulation, Optimal solution, unbalanced transportation problem, Degeneracy, Variants of Assignment Problem-Traveling Salesman problem. (7)Game theory: Minimax (maximin) Criterion and optimal strategy, Solution of games with saddle points, Rectangular games without saddle points, 2 X 2 games - dominance principle – m X 2 & 2 X n games and graphical method. Theory of replacement of Equipment that fails suddenly, Group Replacement. (9)Waiting lines: Single Channel – Poisson arrivals – exponential service times – with infinite population and finite population models. (6)Inventory models: Introduction, terminology, EOQ, deterministic models — Instantaneous production
Course ObjectiveThe objective of this course is to introduce the concepts of formulating an engineering problem into a mathematical model to develop an optimal solution.Course OutcomesAfter completion of the course student will be able to: 1. Apply linear programming approach for optimizing the objectives of industrial oriented problems. 2. Formulate and solve Transportation Models and assignment Models 3. Implement the strategies in competitive situations and Identify the replacement period of the equipment. 4. Analyze the waiting situations in an organization. 5. Determine the optimum inventory level and resolve the complex problem into simple problems by dynamic programming approach and apply optimum strategies.Contents of the course (With approximate break up of hours)Introduction to Operations Research, operations research models, applications. (2) Linear programming: Formulation, Graphical solution, Simplex method, artificial variables techniques, Two-phase method, Big-M method, Duality Principle. (7) Transportation and Assignment problems: Formulation, Optimal solution, unbalanced transportation problem. (7) Game theory: Minimax (maximin) Criterion and optimal strategy, Solution of games with saddle points, Rectangular games without saddle points, 2 X 2 games - dominance principle - m X 2 & 2 X n games and graphical method. Theory of replacement. (9) Waiting lines: Single Channel - Poisson arrivals - exponential service times - with infinite population and finite population models. (6)Inventory models: Introduction, terminology, EOQ, deterministic models - Instantaneous production, finite production, continuous demand, purchase inventory models with one price break and multiple price breaks. (6)
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Dynamic programming: Introduction, Bellman's Principle of optimality, Applications of dynamic programming, capital budgeting problem, shortest path problem, linear programming problem. (5)
Textbooks and 1. Singiresu S Rao, "Engineering Optimization: Theory and Practice", 4th edition,
References Wiley, 2009.
2. Hiller &Libermann, "Introduction to Operation Research", 9th Edition, McGraw
3 A M Natarajan P Balasubramani A Tamilarasi "Operations Research" 2nd
edition. Pearson Education. 2014
4. Taha, "Introduction to Operation Research, 9th edition, PHI, 2010.

Course Title	Computational Fluid Dynamics	Course Number	ME506T
Course category	PEC	Structure (IPC)	3-0-3
Offered to	B.Tech, MDM	Status (Core/Elective)	Elective
Prerequisite	Fluid Mechanics,	Effective from	July 2019
	Heat Transfer		
Course Objective	The objective of this course is to introc	luce the numerical technique	ues and its role in the
	field of heat transfer and fluid flow.	Also, to enable the studen	its to understand the
	various discretization methods and met	thodologies.	
Course Outcomes	After completion of the course student	will be able to:	
	1. Formulate the basic fluid dynamics problem mathematically		
	2. Analyze the mathematical behaviour	of partial differential equa	tions
	3. Understand various solution method	ologies.	
	4. Apply the FDM and FVM technique	es to solve heat transfer pro	blems.
	5. Solve the elementary incompressible	e fluid problems using the (CFD techniques
Contents of the course	Basics of Computational fluid dynamic	cs, Governing equations of	fluid mechanics and
(With approximate	heat transfer, Physical boundary conditions - elliptic, parabolic and hyperbolic		
break up of hours)	equations, Finite different formulation, stability analysis (6)		
	Solution methodologies, Direct and iterative methods. Themes elective relevation		
	Solution methodologies: Direct and it	erative methods, Thomas a	algorithm, relaxation
	method, alternating direction implicit n	nethod. (8)	
	Finite difference and finite volume for	rmulation of standy/trans	ant one dimensional
	conduction equation grid generation (10)	lent one-unnensional
	conduction equation, grid generation. (10)	
	Finite volume formulation of steady one-dimensional convection and diffusion		
	problems central unwind hybrid and nower-law schemes: Discretization equations		
	for two-dimensional convection and di	fusion (10)	erenzation equations
	Numerical methods for Navier-Stokes	equation - Turbulence m	odels [,] mixing length
	model. Two equation (k-epsilon) mode	el (8)	ourige manage rengen
Textbooks and	1. Patankar. S. V. "Numerical Heat Tra	unsfer and Fluid Flow". CR	C Press, 1980.
References	2. H. Versteeg, W. Malalasekera, "An	Introduction to Computation	onal Fluid Dynamics:
	The Finite Volume Method", 2nd Editi	on, PHI, 2007	ý
	3. J. D. Anderson, "Computational Flu	uid Dynamics - Basics wit	th Applications", Mc
	Graw Hill, 1995.	•	
	4. K. Muralidhar, T. Sundararajan, "C	Computational Fluid Flow	and Heat Transfer",
	Narosa Publishing House, 1995.	-	
	5. T. K. Sengupta, "Fundamentals of	f Computational Fluid Dy	namics", University
	Press, 2004.	- •	

Course Title	Optimization techniques for Mechanical Engineers	Course Number	ME507T
Course category	PEC	Structure (IPC)	3-0-3
Offered to	B.Tech All Branches	Status (Core/Elective)	Free Elective
Prerequisite	Calculus,	Effective from	July 2019
•	Differential Equations		-
Course Objective	The objective of this course is to mal	ke the students of Mechar	nical Engineering be
	aware of the optimization problems and	l available mathematical to	ols to solve them.
Course Outcomes	After completion of the course student	will be able to:	
	1. Familiarize with the curve fitting techniques.		
	2. Understand the concepts and need fo	r optimisation.	
	3. Familiarize with the various calc	culus and search techniq	ues of optimisation
	problems.		
	4. Familiarize with the Non-traditional	optimisation techniques.	
Contents of the course	Introduction: Introduction to system de	esign, Morphology of desig	gn with a flow chart,
(With approximate	Concept of workable design, practica	al example on workable	system and optimal
break up of hours)	design. (4)		
	System Simulation: Successive substitution method, Newton Raphson method: One		
	and Multiple unknowns, Gauss Siedel	method, Rudiments of fini	te difference method
	for partial differential equations, with e	xamples. (5)	
	Regression and Curve Fitting: Need	for regression in simulation	on and optimization;
	Concept of best fit and exact fit; Concept of least square regression fit; Gauss Newton method for poplinger least squares regression (7)		
	method for nommear least squares regression (7)		
	Optimization: Basic ideas, Need for optimisation, formulation, graphical method,		
	linear programming problems, simple	ex method, Types of opt	imisation problems:
	Calculus methods; Lagrange multiplier	s, search techniques, local	and global optimum.
	(18)		
	Non-traditional optimization technique	es: Genetic Algorithms, S	imulated Annealing,
	Particle swam optimisation algorithm,	Artificial Neural networks.	(8)
Textbooks and	1. C. Balaji, "Essentials of Thermal S	System Design and Optimiz	zation", 2nd Edition,
References	Ane Books, 2019. 2 Kalvanmov Dah "Ontimization	for Engineering Desig	n: Algorithms and
	Examples" 2nd edition Prentice H	all India 2012	n. Algoriumis and
	3 S S Rao "Engineering Optimiz	ation: Theory and Practice	". 4th edition John
	Wiley & Sons, 2009	interior interior	, conton, com
	4. Yogesh Jaluria, "Design and Opti	mization of Thermal Syste	ems", McGraw Hill.
	1998.		. , ,

Course Title	Automobile Engineering Systems	Course Number	ME508T
Course category	PEC	Structure (IPC)	3-0-3
Offered to	B.Tech All Branches	Status (Core/Elective)	Free Elective
Prerequisite	Nil	Effective from	July 2019
Course Objective	The objective of this course is to learn about the automobile layout, Engine Emissions, working of Transmission system, Steering system, Suspension system, Braking system, Fuel system and different Electrical systems.		
Course Outcomes	 After completion of the course student will be able to: 1. Acquire the basic knowledge of anatomy of an Automobile and its components. 2. Understand the working principles of suspension, transmission, control systems of an automobile. 3: Realize the functions of various electrical and electronic systems used in automobiles. 4: Understand the role of alternative flues and pollution free vehicles. 		
Contents of the course (With approximate break up of hours)	Introduction: Principles of Engine operation, engine parts, cooling systems, lubrication systems, fuel systems, Emission standard and Testing. (10) Structures: Construction, function, loading, principles of suspension systems and mechanics. (6)		
	Vehicle controls: Steering geometry a Auto electrical and electronics: Ba ignition, Electronic Fuel injection. (6) Alternative concepts: Alternative fue	and types, Brakes- types and attery generator, starting bels, basics of electric and b	d construction. (6) motor, lighting and hybrid vehicles, fuel
	cells. (8)		
Textbooks and References	 J. Heitner, "Automotive Mechanics H. Heisler, "Advanced Vehicl Heinemann Series, 2002. Kirpal Singh, "Automobile Engin Publishers Distributors, 2014. David A Crolla, "Automotive Eng series, 2009. "Automotive handbook", 3rd Edition 	s", 2nd Edition, CBS Publis le Technology", 2nd Ec neering - Vol I & II", 13 gineering", 1st edition, But on, Robert Bosch GmbH, S	sher, 2006. dition, Butterworth- ^{3th} Edition, Standard terworth-Heinemann A.A.E., 1993.

Course Title	Nonlinear Dynamics	Course Number	ME509T
Course category	PEC	Structure (IPC)	3-0-3
Offered to	B.Tech All Branches	Status (Core/ Elective)	Free Elective
Prerequisite	Linear Algebra	Effective from	July 2019
Course Objective	The objective of the course is to prov	vide the primary tools to de	eal with the nonlinear
	dynamical equations from various physic	cal scenarios.	
Course Outcomes	After completing this course, the student	t will be able to:	
	1. Interpret the nonlinear dynamical eq	uation geometrically	
	2. Understand the system qualitatively	without solving the nonlinea	r system.
	3. Understand the deep simplicity in th	e chaotic system.	
Contents of the	Introduction to nonlinear dynamics; Flows on the line - geometrical way of thinking,		
course	Linear stability analysis, existence and uniqueness. (5)		
(With approximate			
break up of hours)	Bifurcations – saddle node, trans-critica	l, pitch fork; Flow on the cur	ve – uniform and non-
	uniform oscillator (10)		
	Linear two-dimensional systems – classification; Phase plane – phase portrait, fixed points		
	and linearization, conservative systems. (5)		
	Limit cycles – Ruling out closed orbits, Poincare – Bendixson theorem, Lienard systems,		
	Relaxation Oscillators, Weakly nonlinear oscillators; Hopf bifurcation, Global bifurcation		
	of cycles, Poincare map (10)		
	T	1D	The desired and
	Lorenz equation, chaos on a strange at	tractor, Lorenz map; 1D ma	$ps - Fixed points and p_{12}$
Taythooks and	1 Stoven U Strogetz "Nonlinger Dung	wind and Choos" Dersous he	$\frac{12}{200}$
Deferences	1. Steven in Strogatz, Nonlinear Dyna	unics and Chaos, Perseus DC	OUKS, 1994.
References	2. J D Murray, Mainematical Biology	– an introduction, springer	•

Course Title	Operations and Supply Chain	Course Number	ME510T
Course estagory		Structure (IDC)	303
Offered to	P Tech All Propohos	Stratus (Core/Elective)	5-0-5 Erec Elective
Diference lo	Linear Algebra	Effective from	Free Elective
Course Objective	This course introduces the basics of On	Chair Chair	July 2019
	concepts in Operations Management at decisions within an organization while the organizations.	re restricted to the plann he supply chain concepts a	ing and operational are for a network of
Course Outcomes	 After completion of the course student will 1. Apply the forecasting techniques in esti 2. Use the inventory management technimaterial. 3. Decide the dispatch procedure required 4. Acquaintance to the concepts Supply children for forecasting. Quantity 	Il be able to: imating the number of production niques to determine the of for a production processes nain Management tative methods (3)	ucts. ptimum quantity of and other activities.
course (With approximate break up of hours)	nate urs) Forecasting, Qualitative methods. (5) Facility layout and location: Qualitative aspects, Quantitative models for la decisions, Product, process xed position, group layout, Location decisions-quantitative models. (6)		models for layout ecisions-quantitative
	 Capacity and aggregate planning, Capacity measurement, Long-term and short-term strategies, Aggregate planning. (3) Inventory management: Various costs in inventory management and need, Deterministic models and discounts, Probabilistic inventory management. (6) Scheduling models and applications, Scheduling in MRP system, Sequencing rules and applications, Batch production sequencing and scheduling. (4) Introduction to supply chain: Definition, complexity, key issues, Centralized vs. decentralized systems. (3) 		
	Value of information and supply chain integration: Bullwhip effect, Push-based, pull based systems. Outsourcing: Make or buy decisions. Transportation decision: Drivers of the decision, Network design decisions, Cross-docking, trans-shipment. (8)		
	Distribution and logistics in supply chains: Direct shipment/intermediate storage policies, Vehicle routing models, Third-party logistics. (5)		
	Information technology in supply chain, Enabling supply chain through IT, ER platforms, Service oriented architecture (SOA), RFID (4)		
Textbooks and References	 R. Panneerselvam, Production/Operation 2007. P.Rama Murthy, Production and Operate Edition, 2005. S.N.Chary, Production and Operations 2 4. Samuel Eilon, Elements of Production Corporation, 2004. 	ons Management, Prentice H tions Management, New A Management, TMH, 4th Ed n Planning and Control, U	Hall of India Pvt Ltd, ge International, 2nd lition 2010. Universal Publishing
	5. Joseph.G.Monks, Operations Managem	ent, McGraw-Hill Inc., 3rd	Revised edition.