(12) PATENT APPLICATION PUBLICATION

(19) INDIA

(22) Date of filing of Application :20/09/2023

(21) Application No.202341063258 A

(43) Publication Date : 06/10/2023

(54) Title of the invention : TRANSFEMORAL PASSIVE PROSTHETIC LEG MECHANISM FOR USER POWERED WALKING GAIT GENERATION

(51) International classification : A61F0002600000, A61F0002640000, A61F0002500000, A61F0002760000, A61F0002680000	(71)**Name of Applicant :**
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(86) International Application No : NA Filing Date : NA	
(87) International Publication No : NA	
(61) Patent of Addition to Application Number : NA Filing Date : NA	
(62) Divisional to Application Number : NA Filing Date : NA	

(57) Abstract :
The proposed invention relates to a mechanism and more particularly to a Transfemoral Prosthetic Leg Mechanism for User Powered Walking Gait Generation (0) based on the principle of quick return mechanism and cross belt drive mechanism which constitute a single degree of freedom. The prosthetic leg (0) has a belt or a harness (1) worn by the user at the waist attached over the socket (18) with a cavity supported by shank/pylon (17) with the quick return mechanism as crank disc (4), slotted bar (5) connecting rod (6) to provide oscillating motion to the knee (10) which further provide motion to the foot joint (14) with the help of cross belt drive consists of cross link 1 (7), cross link 2 (8), and crosslink 3 (9) to generate the gait.

No. of Pages : 20 No. of Claims : 8